# Local and global minimality results for a nonlocal isoperimetric problem

#### Massimiliano Morini

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Massimiliano Morini Local and global minimality ... 1/37

Massimiliano Morini Local and global minimality ... 2/37

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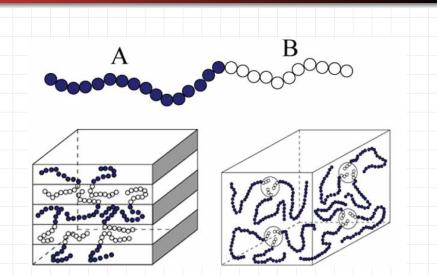
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different volume fractions  $\implies$  different nanostructure

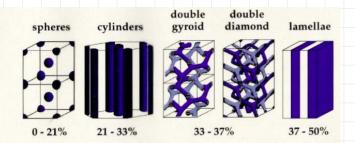
#### Phase boundaries for diblocks



Picture from an article by Choksi, Peletier and Willams 2009

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Tendency towards *periodic* arrays of interfaces– observed experimentally and numerically.



increasing volume fraction of minority phase polymer

Picture from Edwin Thomas' talk at MSRI 1999

Massimiliano Morini Local and global minimality ... 5/37

Denote by  $u: \Omega \rightarrow \mathbb{R}$  the function describing the density:

 $\begin{cases} u(x) \simeq 1 & \text{on phase } A \\ u(x) \simeq -1 & \text{on phase } B \end{cases} \qquad m = \frac{1}{|\Omega|} \int_{\Omega} u \, dx \qquad \text{fixed}$ 

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Here  $G_{\Omega}$  is the Green's function defined by

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and  $\Omega = \mathbb{T}^N$  (PBC) or  $\Omega$  is bounded and (sufficiently) smooth (NBC)

#### The Ohta-Kawasaki functional: the potential v

#### Setting

$$v(x) := \int_{\Omega} G_{\Omega}(x, y) u(y) \, dy \, ,$$

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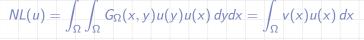
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Remark: We have that

 $\nabla \mathbf{v} \|_{\mathcal{L}^{2}(\Omega)} = \sup \left\{ \left| (u - m) \rho \, d\mathbf{x} : \rho \in H^{1}(\Omega), \| \nabla \varphi \|_{\mathcal{L}^{2}(\Omega)} = 1 \right\}$ 

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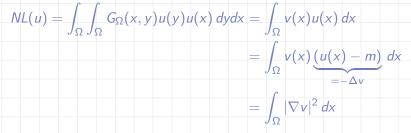
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#### The nonlocal isoperimetric problem–the $\varepsilon \rightarrow 0$ limit of O-K

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The nonlocal isoperimetric problem (NLIP) is given by

minimize  $J(u) := \operatorname{Per}_{\Omega} \left( \{ x : u(x) = 1 \} \right) + \gamma \int_{\Omega} |\nabla v|^2 dx$ , (NLIP)

over all  $u \in BV(\Omega, \{\pm 1\})$  satisfying

$$\oint_{\Omega} u \, dx = m$$

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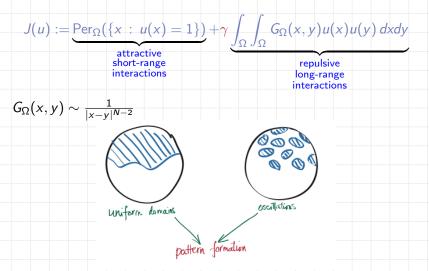
#### NLIP- A 'fight' of low surface area versus high oscillation

 $J(u) := \underbrace{\operatorname{Per}_{\Omega}(\{x : u(x) = 1\})}_{\operatorname{attractive}} + \gamma \underbrace{\int_{\Omega} \int_{\Omega} G_{\Omega}(x, y) u(x) u(y) \, dx dy}_{\operatorname{attractive}}$ short-range repulsive interactions long-range interactions

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#### NLIP- A 'fight' of low surface area versus high oscillation



NLIP is interesting as a canonical nonlocal perturbation of the classical isoperimetric problem; and as a

model for energy-driven pattern formation.

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#### $\min \{J(E) : E \subset \Omega, |E| = m\}$ (NLIP)

#### Mathematical challenges: global minimizers

## Structure of global minimizers: are the global minimizers of $\mathcal{E}_{\varepsilon}$ and of *J* (almost) periodic?

True in one dimension (Muller, 1993);

Partial results in higher dimensions (Alberti-Cheksi-Ottb, 2009; Spadaro, 2009) --- regulatribution of energy

Droplet minimizers: Choksi&Peletier Muratov, Goldman Muratov&Serfaty. Cicalese&Spadaro

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Structure of local minimizers: Can we exhibit local minimizers of  $\mathcal{E}_{\varepsilon}$  and of J that look like lamellae, droplets, gyroids, cylinders....?

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The link is provided via  $\Gamma$ -convergence

#### Theorem (Kohn-Sternberg)

Let (X, d) be a metric space and let  $(F_k)_k$  be a sequence of lower semicontinuous and equi-coercive functionals from X to  $\mathbb{R} \cup \{+\infty\}$ . Assume that  $F_k \xrightarrow{\Gamma(d)} F$  and let x be an isolated local minimizer of F. Then there exist  $x_k \to x$  such that  $x_k$  is a local minimizers of  $F_k$  for k large enough.

## Plan: • show that $\frac{\partial^2 J}{\partial r} > 0 \Rightarrow$ a critical point is an isclated $\frac{L^2}{r} = \frac{1}{r} =$

- thus the known stable critical configurations are isolated
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The Euler-Lagrange equation for  $C^2$  minimizers of J(E) with a volume constraint

$$(E.L.) \qquad \qquad H_{\partial E}(x) + 4\gamma v_E(x) = \lambda \qquad \text{on } \partial E$$

where  $H_{\partial E} =$  sum of principal curvatures

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Natural definition:  $E \subset \Omega$ , is a (strict) local minimizer if  $\exists \delta > 0$  s.t.

J(F) > J(E)

whenever  $F \subset \Omega$  with  $0 < d(E, F) < \delta$  and |F| = |E|

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*E* is a minimizer with volume constraint  $\leftrightarrow$ 

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#### Theorem (Sternberg-Topaloglu (2011))

If  $E \subset \mathbb{T}^n$  is a local minimizer of J, then  $\partial E \setminus \Sigma$  is  $C^{3,\alpha}$ , for any  $\alpha < 1$ , and  $\Sigma$  is a closed set such that  $\dim_{\mathcal{H}}(\Sigma) \leq n-8$ 

Massimiliano Morini Local and global minimality ... 18/37

# Let $E \in C^2$ be critical and fix a $C^2$ vector field $X : \Omega \mapsto \Omega$ . Then, let us consider

 $\Phi: \Omega \times (-1,1) \mapsto \Omega$  the associated flow

$$\frac{\partial \Phi}{\partial t} = X(\Phi), \qquad \Phi(x,0) = x$$

and set  $E_t := \Phi(\cdot, t)(E)$ ,

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Assume that

 $|E_t| = |E|.$ 

## Computation of the second variation

#### Theorem (Choksi-Sternberg 2007)

Here, G(x,

For, say  $\Omega = \mathbb{T}^n$  and  $f := X \cdot \nu_E$ , one can compute second variation

$$\partial^{2} J(f) := \underbrace{\int_{\partial E} \left( |\nabla_{\partial E} f|^{2} - |B|^{2} f^{2} \right) d\mathcal{H}^{n-1}}_{standard second variation of area}$$

$$\underbrace{8\gamma \int_{\partial E} \int_{\partial E} G(x, y) f(x) f(y) d\mathcal{H}_{x}^{n-1} d\mathcal{H}_{y}^{n-1}}_{nonlocal contribution}$$

$$+ \underbrace{4\gamma \int_{\partial E} \nabla v \cdot \nu f^{2} d\mathcal{H}^{n-1}}_{nonlocal contribution}.$$

$$y) = Green's function for (-) Laplacian.$$

Massimiliano Morini Local and global minimality ... 19/37

Since  $J(E) = J(E + t\tau)$ 

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Let us define  $T = \operatorname{span}\{\nu_1, \dots, \nu_n\}$  and

 $T^{\perp} = \{f \in H^1(\partial E) : \int f = \int f \nu_i = 0\}$ 

Since  $J(E) = J(E + t\tau)$ 

$$\implies \partial^2 J(E)[ au \cdot 
u_E(x)] = 0$$
 for all  $au$ 

Let us define  $T = \operatorname{span}\{\nu_1, \dots, \nu_n\}$  and

$$T^{\perp} = \{f \in H^1(\partial E) : \int f = \int f 
u_i = 0\}$$

Strict stability then means

$$\partial^2 J(E)[f] > 0 \quad \forall f \in \mathcal{T}^\perp \setminus \{0\}$$

#### L<sup>1</sup> local minimality via second variation

Theorem (Acerbi-Fusco-M., Comm. Math. Phys 2013)

Let  $E \subset \mathbb{T}^n$  be a regular critical set of J such that

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There exists  $\delta > 0$  s.t. for all  $F \subset \mathbb{T}^n$  with |F| = |E| and  $d(E, F) < \delta$ 

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Extension to NBC: Julin-Pisante, 2013

## Consequences: the Ohta-Kawasaki energy

#### Proposition

If E is a regular critical point of J with  $\partial^2 J(E) > 0$ , then there exists a family  $\{u_{\varepsilon}\}_{\varepsilon < \varepsilon_0}$  of strict local minimizers of the diffused energy  $\mathcal{E}_{\varepsilon}$  with  $\int_{\mathbb{T}^n} u_{\varepsilon} dx = \int_{\mathbb{T}^n} u_E dx$ , s.t.

 $u_{\varepsilon} \rightarrow u_E$  in  $L^1(\mathbb{T}^n)$ 

as  $\varepsilon \rightarrow 0$ .

## Case $\gamma = 0$ : the periodic isoperimetric problem

#### Corollary

Let  $E \subset \mathbb{T}^n$  be smooth open set with  $\partial E$  a constant mean curvature surface. If

 $\int_{\partial E} \left( |\nabla_{\partial E} f|^2 - |B_{\partial E}|^2 f^2 \right) d\mathcal{H}^{n-1} > 0 \qquad \forall f \in T^{\perp}(\partial E) \setminus \{0\},$ 

then there exist  $\delta$ , C > 0 s.t. for  $F \subset \mathbb{T}^n$ , with |F| = |E| and  $d(E, F) < \delta$ 

 $P_{\mathbb{T}^n}(F) \geq P_{\mathbb{T}^n}(E) + C[d(E,F)]^2$ .

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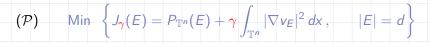
• Morgan-Ros, 2010: local minimality w.r.t.  $L^1$  perturbations but for  $n \leq 7$  and without quantitative estimate

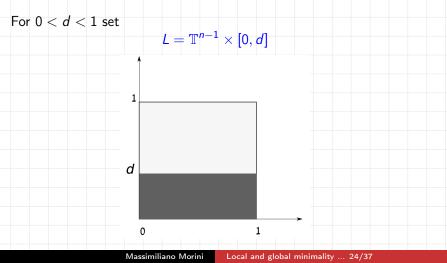
#### Application: Global minimality of the single lamella

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(P) Min 
$$\left\{ J_{\gamma}(E) = P_{\mathbb{T}^n}(E) + \gamma \int_{\mathbb{T}^n} |\nabla v_E|^2 dx, \quad |E| = d \right\}$$

#### Application: Global minimality of the single lamella





#### Theorem (Acerbi-Fusco-M.)

Assume that L is the unique, up to translations and relabelling of coordinates, global minimizer of the periodic isoperimetric problem. Then L is also the unique global minimizer of ( $\mathcal{P}$ ), provided  $\gamma$  is sufficiently small.

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**Step 4:** For  $\gamma$  small *L* is an  $L^1$  isolated local minimizer, uniformly in  $\gamma$ . Thus  $E_{\gamma} = L$  for  $\gamma$  small.

Let n = 2. Theorem + Howards-Hutchings-Morgan, 1999

If  $\frac{1}{\pi} < d < 1 - \frac{1}{\pi}$ , *L* is the unique global minimizer of ( $\mathcal{P}$ ) in  $\mathbb{T}^2$  provided  $\gamma$  is small (see also Sternberg-Topaloglu, 2011)

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Massimiliano Morini Local and global minimality ... 26/37

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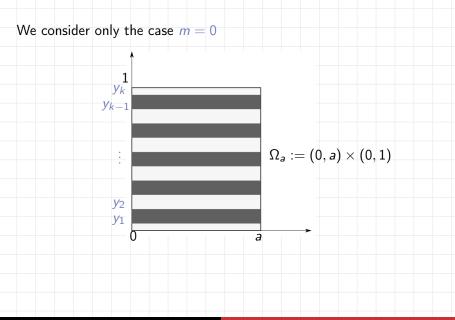
There exist  $\varepsilon_0, \gamma_0 > 0$  s.t. if  $\frac{1}{2} - \varepsilon_0 < d < \frac{1}{2} + \varepsilon_0, \ 0 \leq \gamma < \gamma_0$ 

L is the unique global minimizer of  $(\mathcal{P})$  in  $\mathbb{T}^3$ 

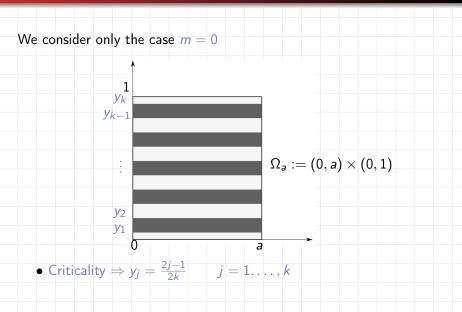
#### Critical 2d k-lamellar patterns

We consider only the case m = 0

#### Critical 2d k-lamellar patterns



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Theorem (M.-Sternberg, 2013)

For any positive integer k,

Massimiliano Morini Local and global minimality ... 28/37

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then the k-lamellar critical point  $u_k$  is an isolated L<sup>1</sup>-local minimizer in  $\Omega_a := (0, a) \times (0, 1)$ ; i.e., there exist  $\delta$  and C > 0 such that

$$J(w) \ge J(u_k) + C \|u_k - w\|_{L^1(\Omega_a)}^2$$

provided  $||u_k - w||_{L^1(\Omega_a)} < \delta$  and  $\int_{\Omega_a} w = \int_{\Omega_a} u_k$ .

• Spectral analysis:  $a < \pi \sqrt{\frac{k}{2\gamma}}$  implies that

 $\partial^2 J(u_k)[f] > 0$  for all  $f \in H^1(\Gamma) \setminus 0$  with  $\int_{\Gamma} f \, d\mathcal{H}^1 = 0$ .

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 Remark: Morphological instability may only come from wriggling and corrugations:

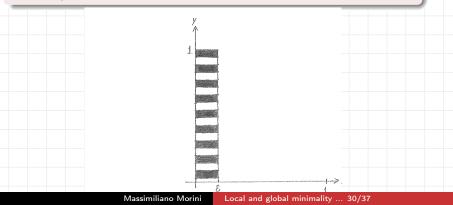
### Cascade of lamellar global minimizers in thin rectangles

#### Theorem (M.-Sternberg, 2013)

Fix any  $\gamma > 0$ . Then for  $k(\gamma)$  minimizing the 1d energy

$$J^{1d}(u_k)=k+\frac{\gamma}{12k^2},$$

 $u_{k(\gamma)}$  is the unique global minimizer of J in  $(0, \varepsilon) \times (0, 1)$  for  $\varepsilon$  sufficiently small.



#### Step 1: Γ-convergence

Consider (NLIP) posed on a thin rectangle  $\Omega_{\varepsilon} := (0, \varepsilon) \times (0, 1)$ :

$$\min \quad J_{\Omega_{\varepsilon}}(u) := \operatorname{Per}_{\Omega_{\varepsilon}}\left(\{x : u(x) = 1\}\right) + \gamma \int_{\Omega_{\varepsilon}} |\nabla v|^2 dx,$$

under the constraint  $\int_{\Omega_c} u = 0$ .

After rescaling onto the (fixed) unit square  $\Omega_1$  and dividing by  $\varepsilon$ one checks that  $J_{\Omega_2}$  F-converges as  $\varepsilon \to 0$  to the one-dimensional energy

$$\int^{1d}(u) := \# \text{ of jumps} + \gamma \int_{0}^{1} v_{y}^{2} dy$$

for  $u \in \mathbb{R} \setminus \{(0, 1), \{-1\}\}$ , with  $\int_0^1 u(y) dy = \emptyset$ , and where

v = v(v) solves

#### +v'' = u for 0 < y < 1, v'(0) = 0 = v'(1).

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$$J^{1d}(u) := \# \text{ of jumps } + \gamma \int_0^{\infty} v_y^2 \, dy$$

for  $u \in BV((0,1); \{\pm 1\})$ , with  $\int_0^1 u(y) dy = 0$ , and where v = v(y) solves

$$-v'' = u$$
 for  $0 < y < 1$ ,  $v'(0) = 0 = v'(1)$ .

"Perimeter" in 1d just counts number of jumps, located say at  $\{y_j\}_{j=1}^k$ .

Also criticality condition  $\kappa + 4\gamma v = constant$  reduces to simply

 $v(y_j) = constant$  (since curvature = 0)

Easily check that only critical points are  $a_k$  given by

where  $y_i := \frac{2j+1}{2k}$  for j = 1, 2, ..., k and the derivative of the corresponding  $v_k$  is a 'sawtooth function."

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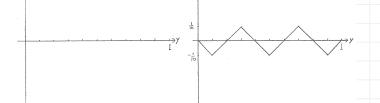
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Easily check that only critical points are  $u_k$  given by

 $u_k(y) := \begin{cases} 1 & \text{for } 0 < y < y_1, \ y_2 < y < y_3, \dots, \ y_{k-1} < y < y_k \\ -1 & \text{for } y_1 < y < y_2. \ y_3 < y < y_4, \dots, \ y_k < y < 1 \end{cases}$ 

where  $y_j := \frac{2j+1}{2k}$  for j = 1, 2, ..., k and the derivative of the corresponding  $v_k$  is a "sawtooth function." (For simplicity only, fix m = 0.)



The 5-jump critical point  $u_5$  with m = 0 and the derivative of the corresponding  $v_5$  solving

$$-v_5'' = u_5$$
 for  $0 < y < 1$ ,  $v_5'(0) = 0 = v_5'(1)$ .

Easy to compute that

$$J^{1d}(u_k) = k + \frac{\gamma}{12k^2}$$

so given any  $\gamma,$  one can optimize over k to find global minimizer is  $u_{k(\gamma)},$  with

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### Step 3: Proof of global minimality

Fix  $a < \pi \sqrt{\frac{k(\gamma)}{2\gamma}}$ . Let  $u_{\varepsilon}$  be a global minimizer in  $\Omega_{\varepsilon}$  and let  $\tilde{u}_{\varepsilon}(x, y) := u_{\varepsilon}(\frac{\varepsilon}{a}x, y)$ 

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By Γ-convergence

 $\widetilde{u}_{arepsilon} o u_{k(\gamma)}$  in  $L^1(\Omega_a)$ 

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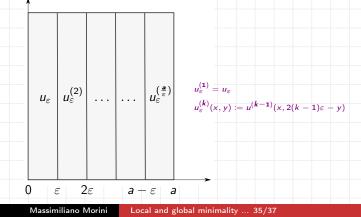
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Let  $u_{\varepsilon}^{r}$  the function in  $BV(\Omega_{a})$  obtained by  $\frac{a}{\varepsilon} - 1$  reflections of  $u_{\varepsilon}$ .



Note  $\|u_{\varepsilon}^{r} - u_{k(\gamma)}\|_{L^{1}(\Omega_{a})} = \|\tilde{u}_{\varepsilon} - u_{k(\gamma)}\|_{L^{1}(\Omega_{a})} \to 0$ 

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Thus for  $\varepsilon$  small enough

$$J_{\Omega_{\boldsymbol{a}}}(u_{\varepsilon}^{r}) \geq J_{\Omega_{\boldsymbol{a}}}(u_{k(\gamma)}) + C \left\| u_{k(\gamma)} - u_{\varepsilon}^{r} \right\|_{L^{1}(\Omega_{\boldsymbol{a}})}^{2}$$

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 $\Downarrow$ 

$$u_{\varepsilon} = u_{k(\gamma)}$$
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# Thanks for your attention!!!!!